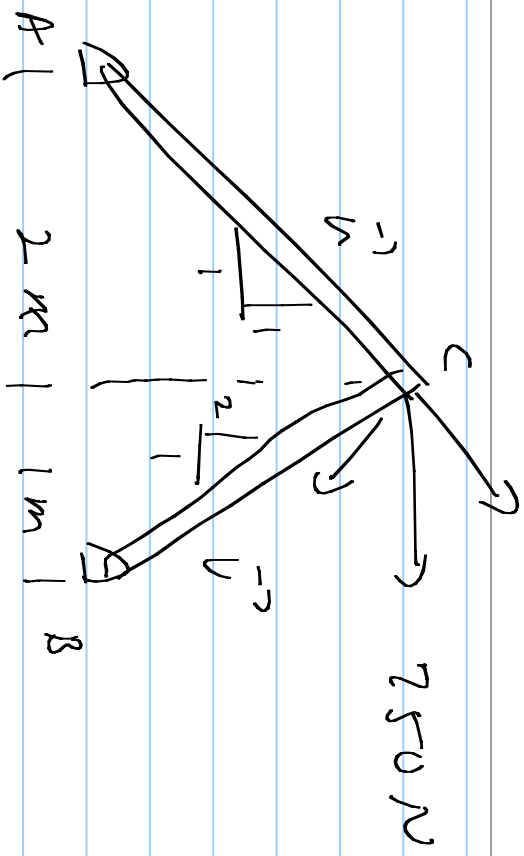


EGR 180 6/1/10

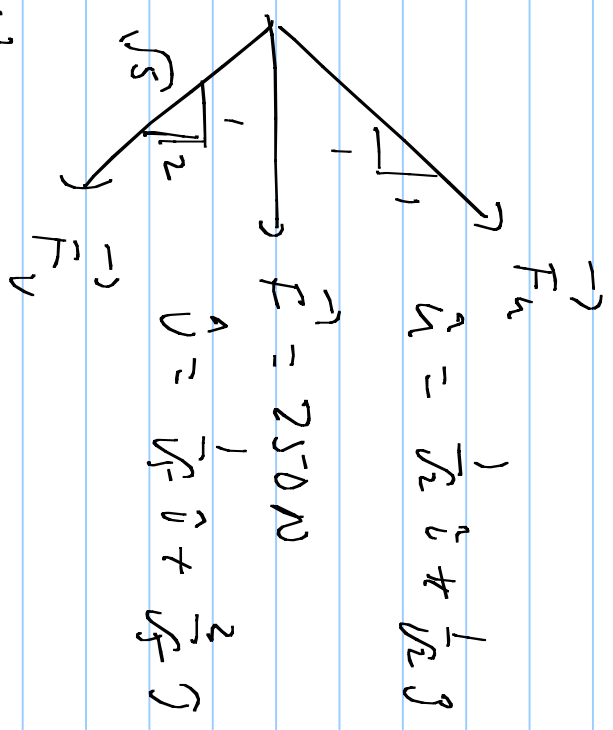
2-42)



$$\vec{F}_u + \vec{F}_v = \vec{F}$$

$$F_u = F \cdot \frac{1}{\sqrt{2}} = \frac{250}{\sqrt{2}} \text{ N} = 177 \text{ N}$$

$$F_v = F \cdot \frac{1}{\sqrt{2}} = \frac{250}{\sqrt{2}} \text{ N} = 177 \text{ N}$$

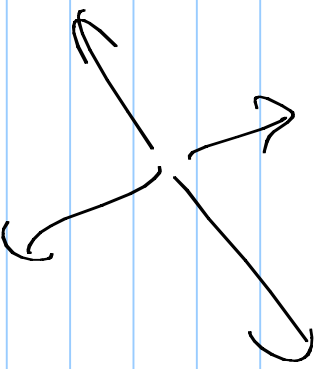


$$\vec{u} = \frac{1}{\sqrt{2}} \hat{i} + \frac{1}{\sqrt{2}} \hat{j}$$

$$\vec{F} = 250 \text{ N}$$

$$\vec{v} = \frac{1}{\sqrt{2}} \hat{i} + \frac{2}{\sqrt{2}} \hat{j}$$

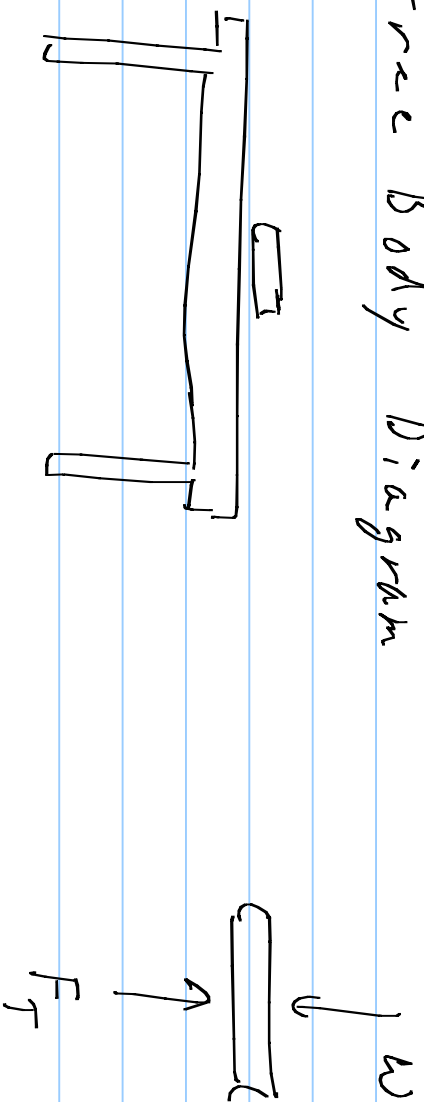
Concurrent Force Systems

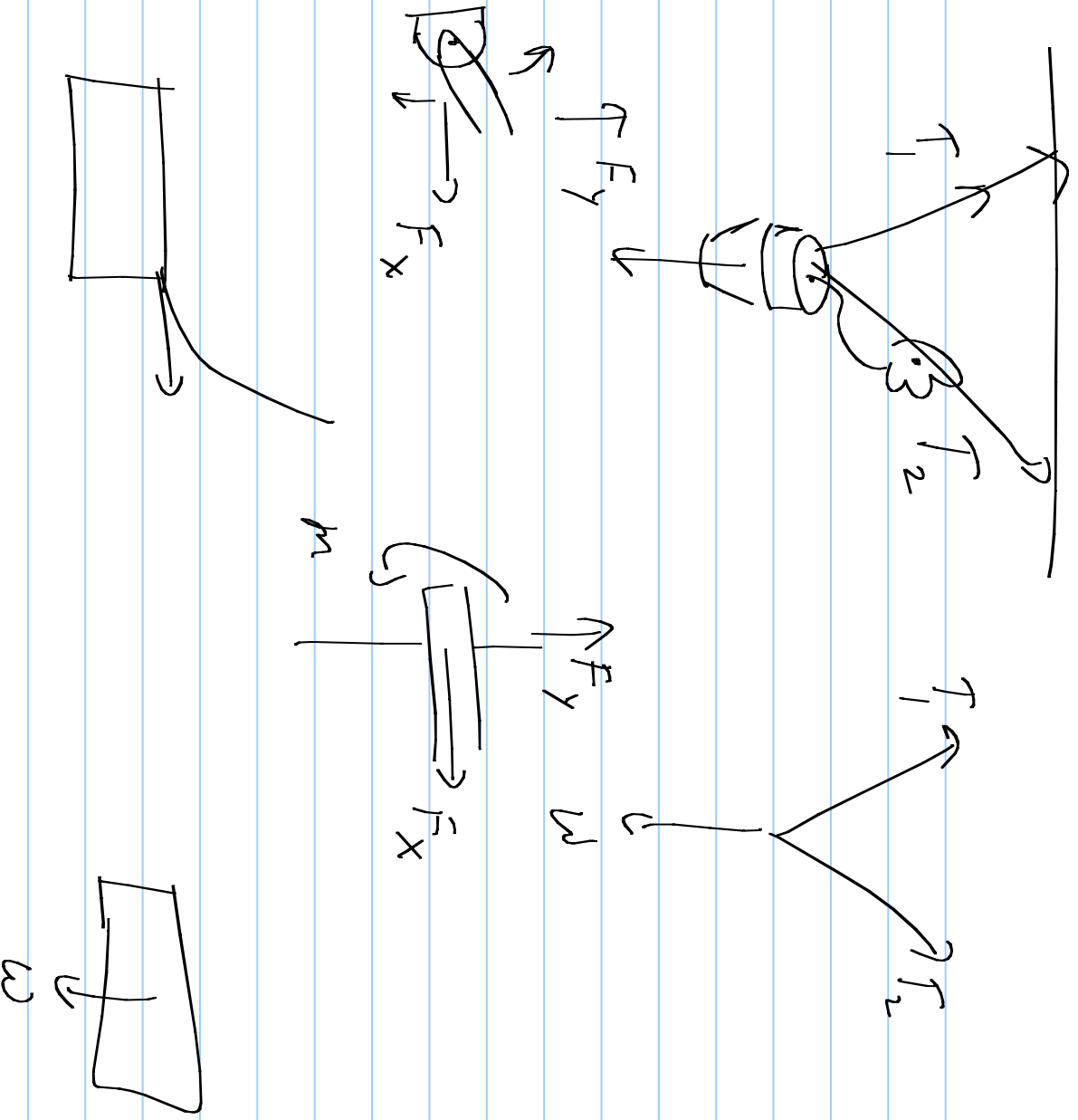


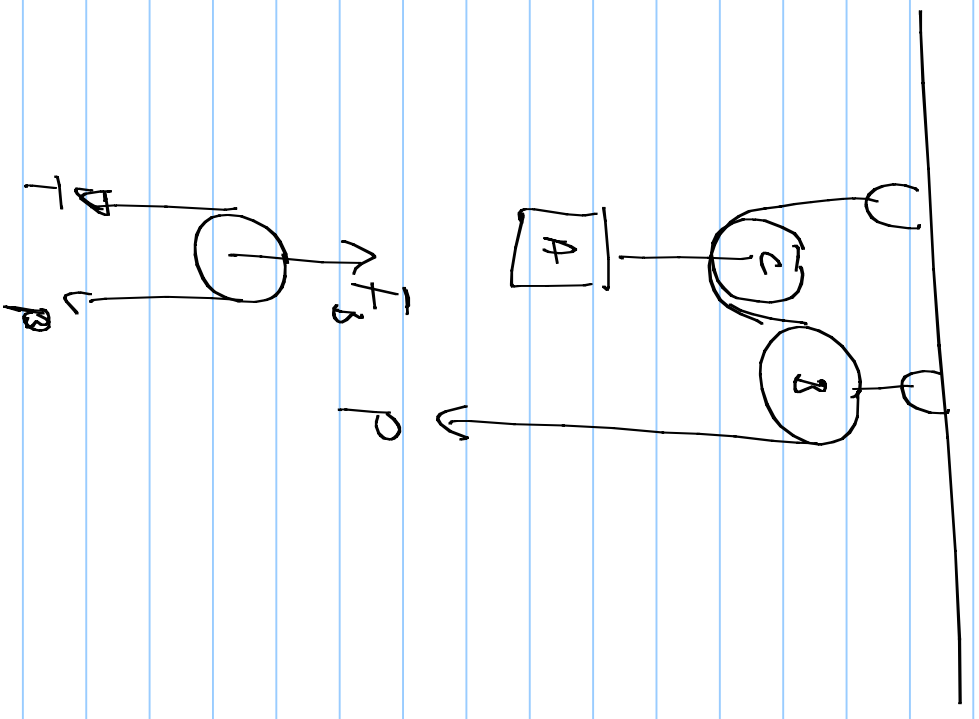
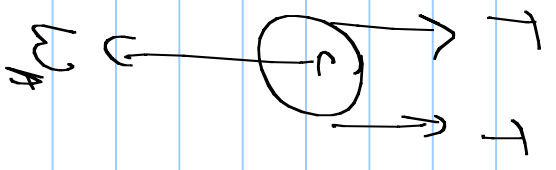
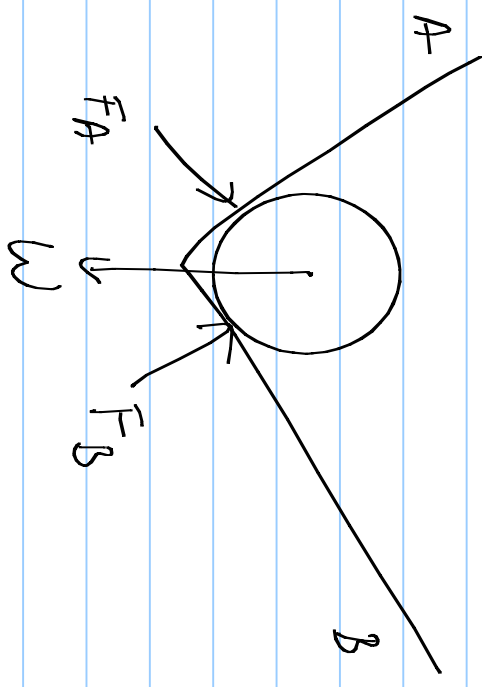
A diagram showing three arrows originating from a single point. One arrow points upwards and to the left, another points upwards and to the right, and a third points downwards. A large curly bracket on the right side of the arrows groups them together.

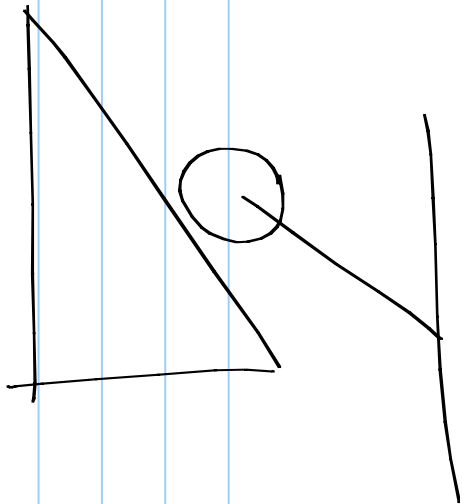
$$\sum F_i = 0$$

Free Body Diagram





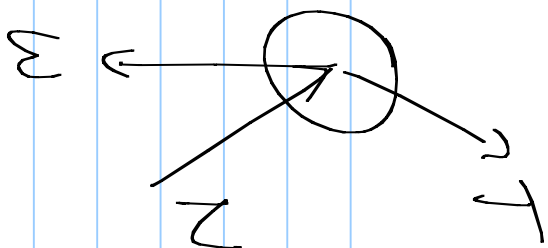




$$\sum F_x = 0$$

$$\sum F_y = 0 \quad \text{At most 3 unknowns}$$

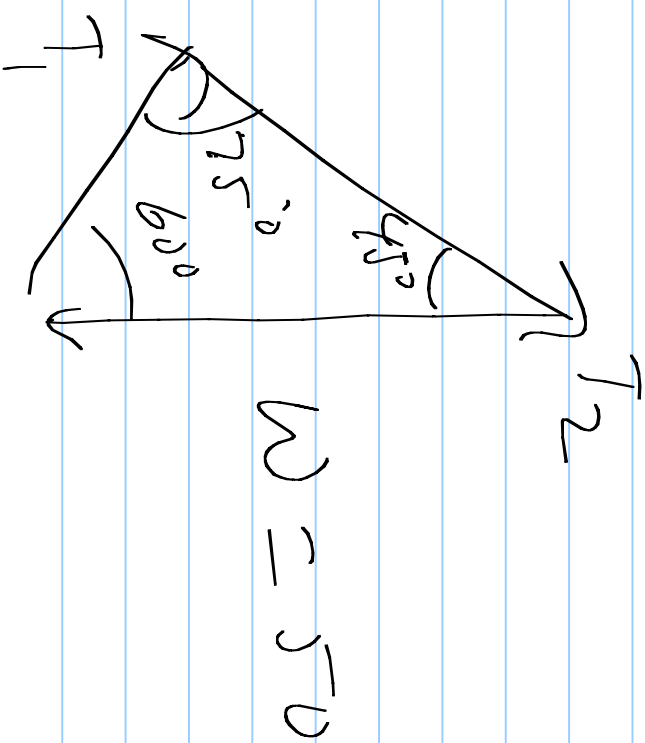
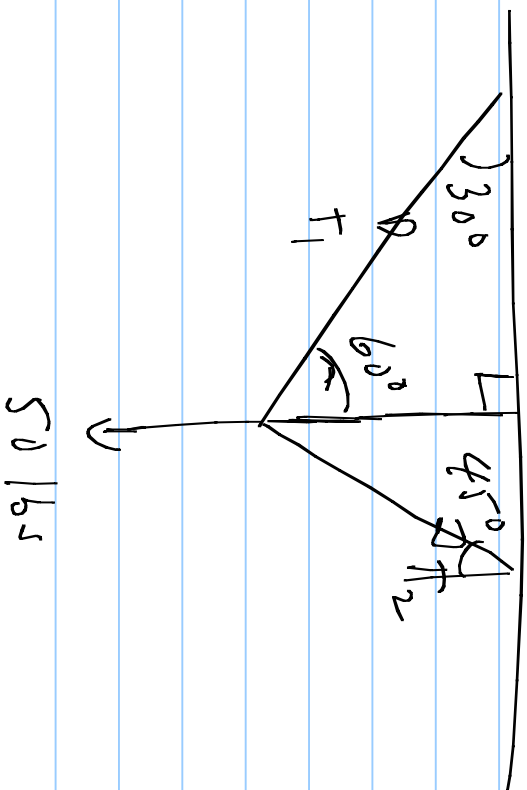
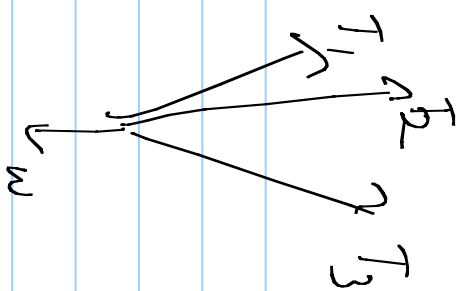
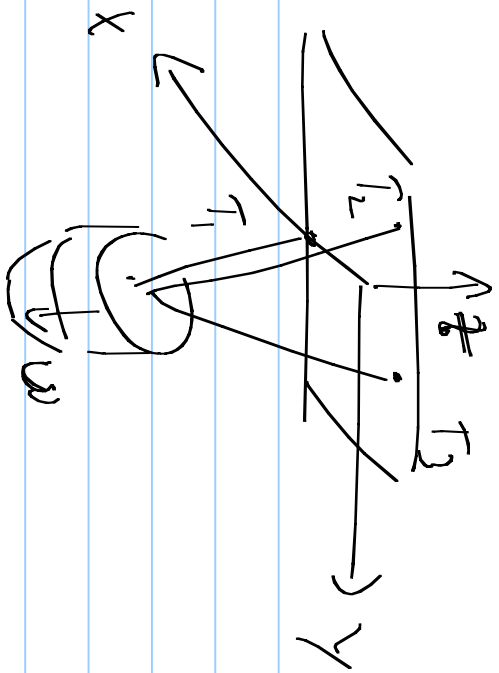
$$\sum F_z = 0$$



$$\sum F_x = 0$$

$$\sum F_y = 0$$

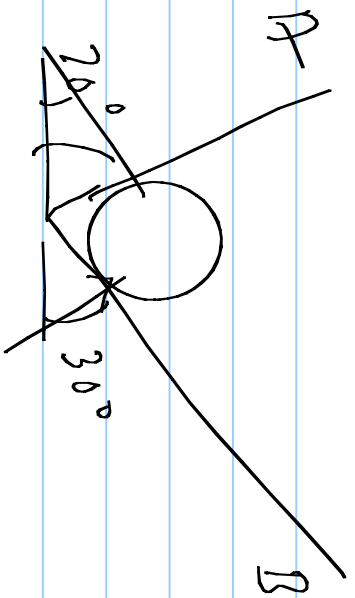
At most 2 unknowns



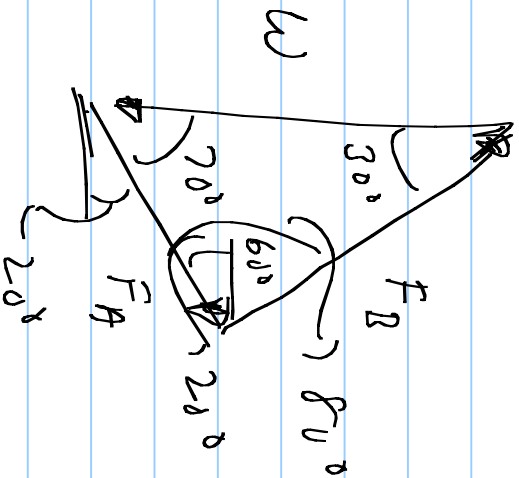
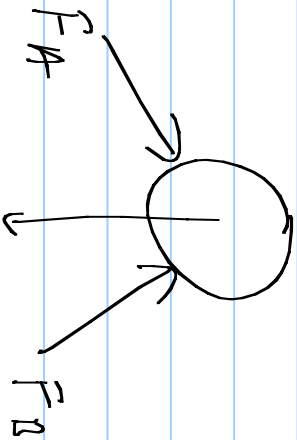
$$\frac{W}{\sin(25)} = \frac{T_1}{\sin(45)} = \frac{T_2}{\sin(60)}$$

$$T_1 = \frac{50 \sin(45)}{\sin(25)} = 36.6 \text{ lbs}$$

$$T_2 = \frac{50 \sin(60)}{\sin(25)} = 44.8 \text{ lbs}$$



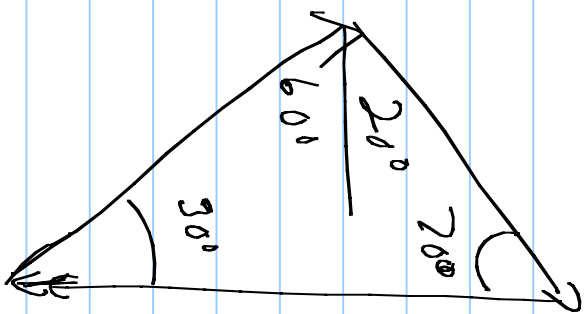
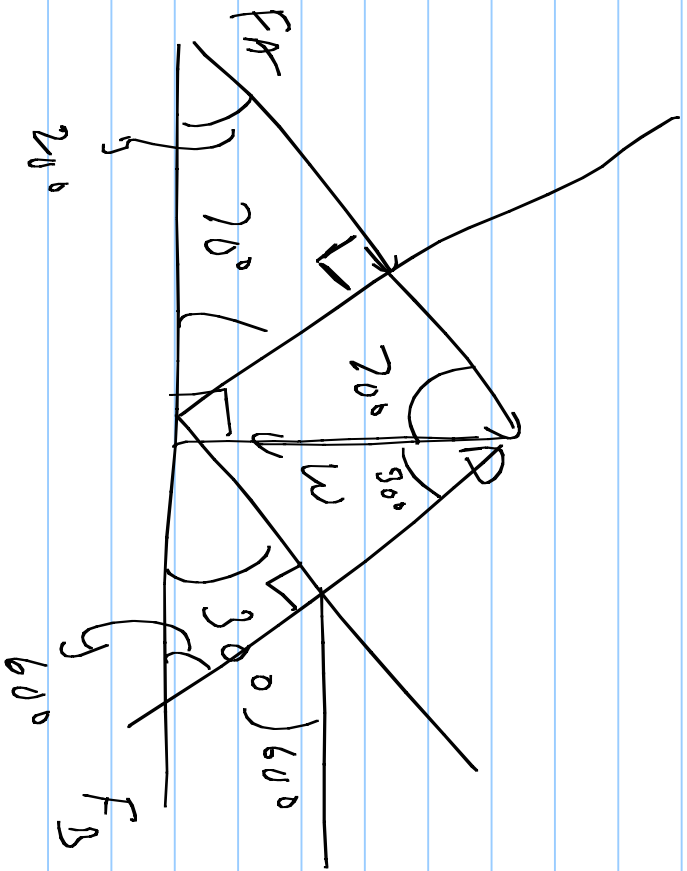
$W = 250 \text{ N}$

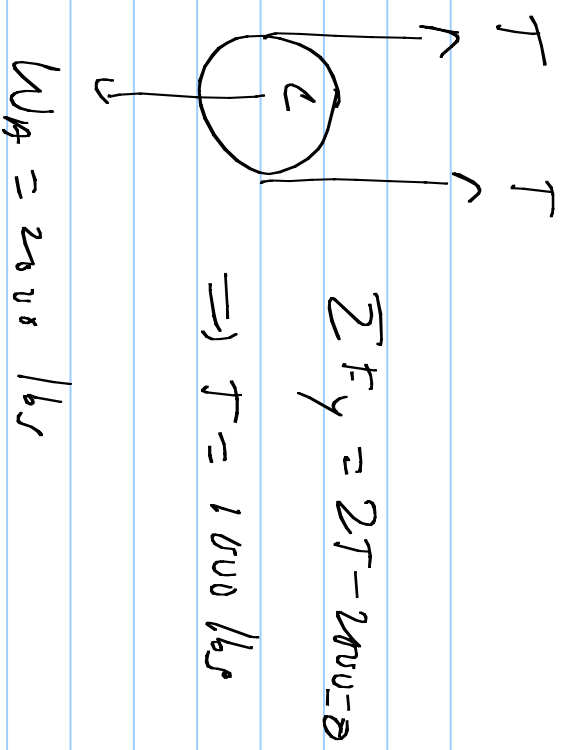
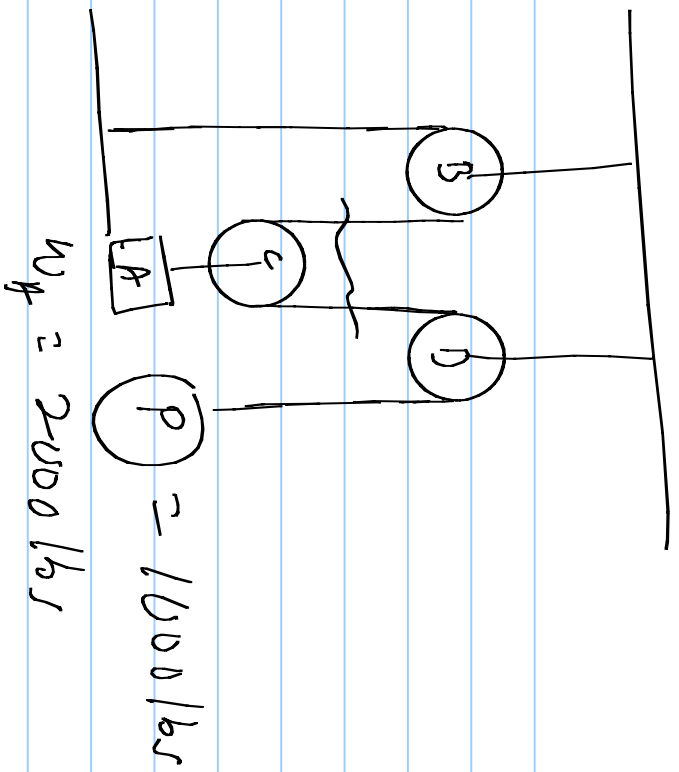


$$\frac{W}{\sin(80)} = \frac{F_A}{\sin(30)} = \frac{F_B}{\sin(20)}$$

$$F_A = \frac{250 \sin(30)}{\sin(80)} = 126.9 \text{ N}$$

$$F_B = \frac{250 \sin(20)}{\sin(80)} = 238.5 \text{ N}$$

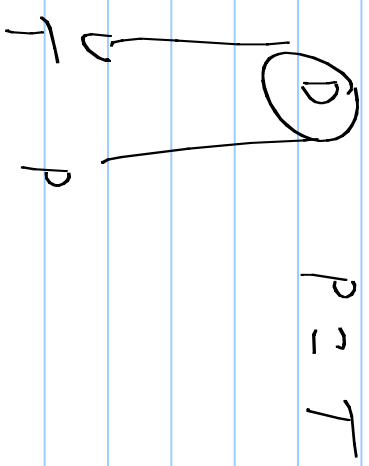




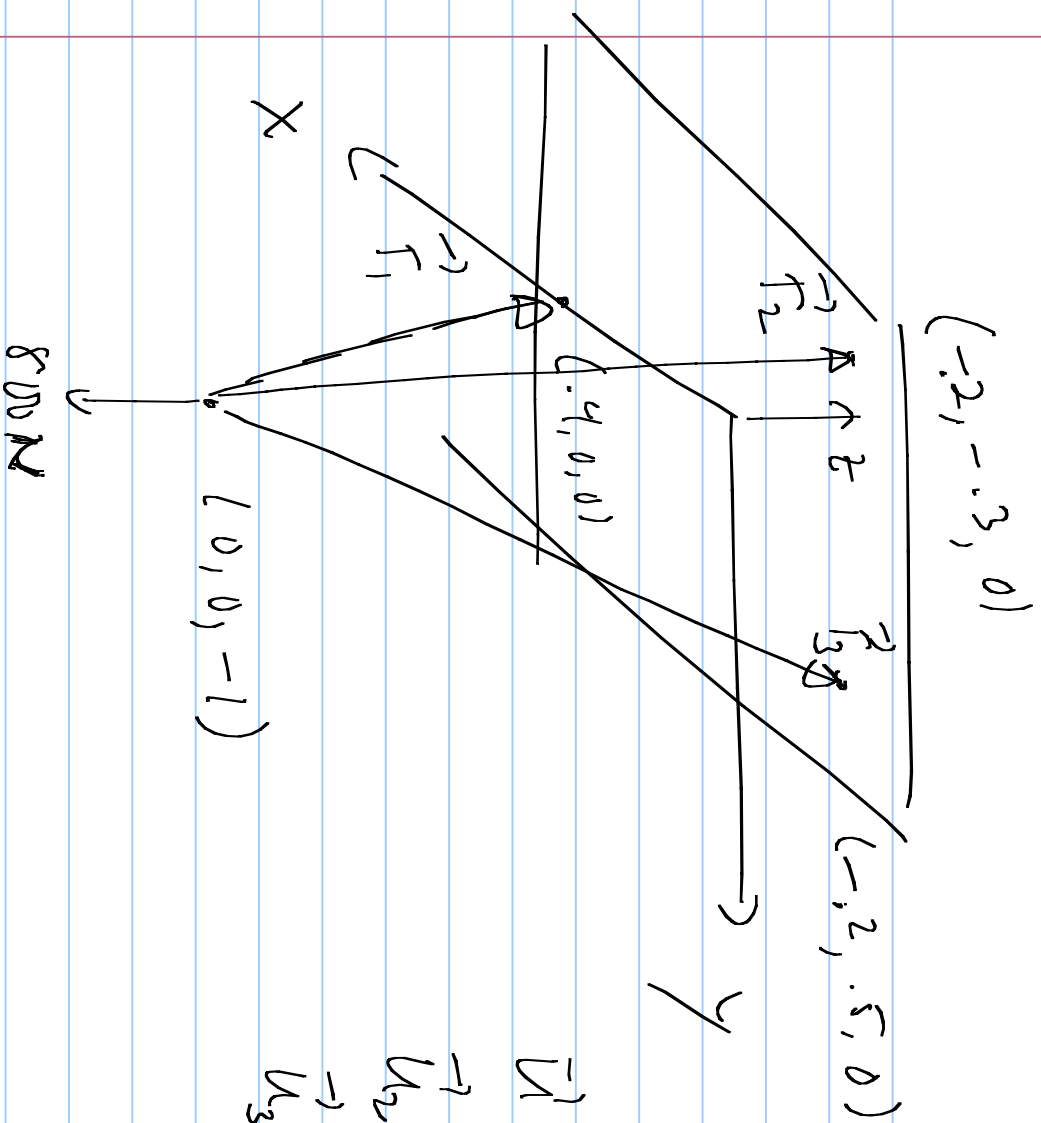
$$\sum F_y = 2T - 2000 = 0$$

$$\Rightarrow T = 1000 \text{ lbs}$$

$$W_A = 2000 \text{ lbs}$$



$$P = T$$



$$\vec{M}_1 = .4\hat{i} + k\hat{j}$$

$$\vec{M}_2 = -2\hat{i} - .3\hat{j} + k\hat{k}$$

$$\vec{M}_3 = -.2\hat{i} + .5\hat{j} + k\hat{k}$$

$$\vec{T}_1 = R_1 \vec{u}_1 = .4R_1 \vec{i} + R_1 \vec{k}$$

$$\vec{T}_2 = R_2 \vec{u}_2 = -.2R_2 \vec{i} - .3R_2 \vec{j} + R_2 \vec{k}$$

$$\vec{T}_3 = R_3 \vec{u}_3 = -.2R_3 \vec{i} + .5R_3 \vec{j} + R_3 \vec{k}$$

$$\sum F_x = .4R_1 - .2R_2 - .2R_3 = 0$$

$$\sum F_y = -.3R_2 + .5R_3 = 0$$

$$\sum F_z = R_1 + R_2 + R_3 - 800 = 0$$